# Lecture 3: Approximation Error

Today:

- Quantify **error** in function approximation
- More key concepts inner product, norm

### Reminder from last week:

Where are we with approximating functions?

**Goal:** find a function,  $f_a(x)$ , that approximates a given function, f(x), accurately on  $x \in [a, b]$ 

x belonging to the interval [a, b] —



How do we address these challenges? What are the key *challenges* to this approach?

There are infinitely many possible functions! Can't handle on a computer



# Stating where we are so far in words

Last time: We used the concepts of vector space and subspace to create a framework for posing the ambiguous aim "I want to be able to approximate any given function" into the concrete, finite-dimensional goal "I want to solve for a finite number of coefficients"

**Today:** We will use the concept of a **norm** to create a framework for characterizing how **accurate** our approximation is.

The norm will be defined in terms of an *inner product*, so we'll start there.

## Inner products

# Inner product



This is a lot to take in at first blush, and is best learned through examples. So let's consider several different cases...

# Inner product: example on $\mathbb{R}^2$

Consider the vector space  $\mathscr{V} = \mathbb{R}^2$  The set of all 2x1 real-valued vectors **Example**:  $\begin{bmatrix} 2\\1 \end{bmatrix}, \begin{bmatrix} -13\\212 \end{bmatrix} \in \mathbb{R}^2$ 

A permissible (and very common) inner product on this space is the function (  $\cdot\,,\,\cdot\,)$  defined by

$$(u, v) = u^T v \text{ for any } u, v \in \mathbb{R}^2$$
(1)

 $u^T v = u_1 v_1 + u_2 v_2$ 

#### Activity:

(A) Show that the proposed function (1) satisfies the properties of an inner product for vectors  $u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ,  $v = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ ,  $w = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$  and your choice of  $\alpha, \beta$ 

(B) Give some physical intuition for what the inner product *means* 

## Inner product: example on $\mathbb{R}^2$ (continued)

(A) We can work through each property one at a time:

(1) 
$$u^{T}v = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = 0$$
 is a scalar number  
(2)  $(v, u) = v^{T}u = \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 0 = (u, v) = \overline{(u, v)}$   
(3) Choosing  $\alpha = 2, \beta = \frac{1}{2}$ , we have that  $(\alpha u + \beta v, w) = \begin{bmatrix} \frac{3}{2} & \frac{5}{2} \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix} = 8$   
But we also have that  
 $\alpha(u, w) + \beta(v, w) = 2\left(\begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix}\right) + \frac{1}{2}\left(\begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \end{bmatrix}\right) = 8 + 0 = 8$   
(4)  $(u, u) = \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 2 > 0$ 

(B) The inner product is a measure of orthogonality between two vectors. The inner product (u, v) was zero for our choice of u and v above because they are perpendicular to one another.

## Inner product: example on $\mathscr{C}[a, b]$

Consider the vector space  $\mathcal{V} = C[a, b]$ 

Consider the candidate inner product defined by

$$(u, v) = \int_{a}^{b} u(x)v(x)dx \text{ for any } u, v \in \mathscr{V}$$
(2)

#### Activity:

(A) Argue for whether the function from (2) is an inner product or not

(B) If it is an inner product, use example 1 as an analogy to give some physical intuition for what the inner product **means** in this function setting

### Inner product: example on $\mathscr{C}[a, b]$ (continued)

(A) We can work through each property one at a time:

(1) For any two continuous functions, taking the proposed integral will give a scalar real number

(2) For any 
$$u, v \in \mathscr{V}$$
,  $\int_{a}^{b} u(x)v(x)dx = \int_{a}^{b} v(x)u(x)dx = (v, u) = \overline{(v, u)}$   
(3)

$$(\alpha u + \beta v, w) = \int_{a}^{b} (\alpha u(x) + \beta v(x))w(x)dx = \alpha \int_{a}^{b} u(x)w(x)dx + \beta \int_{a}^{b} v(x)w(x)dx = \alpha(u, w) + \beta(v, w)$$
(4) For any  $u \in \mathcal{V}$ , note that  $\int_{a}^{b} u(x)u(x)dx = \int_{a}^{b} u(x)^{2}dx \ge 0$   
Moreover, the answer is only zero if  $u(x) = 0$ 

(B) By analogy with example 1, the inner product gives us a generalized measure of orthogonality in this function setting. This ability to connect functions and vectors is powerful and beautiful!

## Inner product: another example on $\mathscr{C}[a, b]$

Consider the vector space  $\mathcal{V} = C[a, b]$ 

### Consider the candidate inner product defined by (u, v) = u(x)v(x) for any $u, v \in \mathcal{V}$ (3)

#### Group activity:

(A) Is the proposed function in equation (3) an inner product?

### Inner product: another example on $\mathscr{C}[a, b]$ (continued)

(A) No, it is not an inner product because it does not obey the first property:

For any  $u, v \in \mathcal{V}$ , (u, v) = u(x)v(x) is a function of x, not a scalar number

## Norm

## Using the inner product to obtain a norm

We have built intuition about inner products, but our original aim was to be able to measure the size of the error in our approximation. That is, how big is  $f - f_a$ ?

The **norm** gives us this answer, and we define the norm from the inner product:

**Definition:** A norm is a function  $|| \cdot ||$  defined on a vector space  $\mathscr{V}$  in terms of an inner product, as

 $||u|| = \sqrt{(u, u)}$  for any  $u \in \mathcal{V}$ 

We can now assess our approximation error,  $e = f - f_{a'}$  via  $||e|| = \sqrt{(e, e)}$ 

#### Some notes:

- By property (4) of an inner product, the norm is non-negative, as desired (can't have a negative size!)
- Using different inner products to induce the norm can help emphasize different things (e.g., in compressible flow, there are debates about whether to induce a norm from mechanical energy or entropy)

# Measuring error with a norm

Consider the inner product defined by

$$(u, v) = \int_{a}^{b} u(x)v(x)dx \text{ for any } u, v \in \mathcal{V}$$
(2)

Define our approximation error as  $e = f - f_a$ 

Recall that a norm on *e* is defined as  $||e|| = \sqrt{(e, e)}$ 

### Activity:

Provide some intuition for why  $||e|| = \sqrt{(e, e)}$  is a useful measurement for how accurate our function approximation is.