Lecture 16: Spectral Methods for BVPs (1)

Today:

- Continue with *boundary value problems* (*BVPs*)
 - This time: don't use finite difference methods.
 - Use *global spectral methods*
 - Analog of least squares function approximation!

Where are we up to now?

Previously.

- (A) We learned how to approximate the solution of a BVP using an FD method
- (B) We learned how to predict the error of that FD method using truncation error and stability

Today. Solutions to BVPs using *global spectral methods*

Philosophy behind spectral methods

Whereas finite difference methods are based on locally interpolating the differential equation, spectral methods minimize the least-squares error in the numerical solution.

This approach is an analog of least squares function approximation (with a prescribed function)!

Because of this strong connection, we will review least-squares function approximation and leverage this to develop global spectral methods

Reminder: least squares function approximation

Goal: find a function, $f_a(x)$, that approximates a given function, f(x), *accurately* on $x \in [a, b]$

- (A)Pick a *subspace* that we want to approximate onto (e.g., $\mathscr{P}^{n}[a, b]$ or $\mathscr{T}^{n}[a, b]$)
- (B) Write $f_a(x)$, as a linear combination of the basis functions in terms of unknown coefficients $f(x) = \sum_{n=1}^{n} c h(x) \qquad (1)$

$$f_a(x) = \sum_{j=0}^{n} c_j b_j(x)$$
 (1)

(C) Need *n* equations to solve for the *n* unknown coefficients. Seek to *minimize the overall error*. That is, we will look for an $f_a(x)$ that satisfies

$$\min_{f_a \in \mathscr{V}} ||f - f_a||^2 \tag{2}$$

(D)Notice that the optimal f_a satisfies

$$(f - f_{a}, b_{i}) = 0, \quad i = 0, \dots, n \quad (3)$$

$$\implies \begin{bmatrix} (b_{0}, b_{0}) & (b_{1}, b_{0}) & \cdots & (b_{n-1}, b_{0}) & (b_{n}, b_{0}) \\ (b_{0}, b_{1}) & (b_{1}, b_{1}) & \cdots & (b_{n-1}, b_{1}) & (b_{n}, b_{1}) \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ (b_{0}, b_{n-1}) & (b_{1}, b_{n-1}) & \cdots & (b_{n-1}, b_{n-1}) & (b_{n}, b_{n-1}) \\ (b_{0}, b_{n}) & (b_{1}, b_{n}) & \cdots & (b_{n-1}, b_{n}) & (b_{n}, b_{n}) \end{bmatrix} \begin{bmatrix} c_{0} \\ c_{1} \\ \vdots \\ c_{n-1} \\ c_{n} \end{bmatrix} = \begin{bmatrix} (f, b_{0}) \\ (f, b_{1}) \\ \vdots \\ (f, b_{n-1}) \\ (f, b_{n}) \end{bmatrix}$$
(4)

(D)Solve for the coefficients \implies we have our f_a

Global spectral methods for BVPs: A least squares method

Goal: find a function, $u_a(x)$, that approximates the BVP solution u(x) accurately on $x \in [a, b]$

- (A)Pick a *subspace* that we want to approximate onto (e.g., $\mathscr{P}^n[a, b]$ or $\mathscr{T}^n[a, b]$)
- (B) Write $u_a(x)$, as a linear combination of the basis functions in terms of unknown coefficients $u_a(x) = \sum_{n=1}^{n} a_n b_n(x)$ (5)

$$u_a(x) = \sum_{j=0}^{n} c_j b_j(x)$$
 (5)

(C) Need *n* equations to solve for the *n* unknown coefficients. Seek to *minimize the overall error*. That is, we will look for an $u_a(x)$ that satisfies

$$\min_{u_a \in \mathscr{V}} ||u - u_a||^2 \tag{6}$$

(D)Notice that the optimal u_a satisfies

$$(u - u_a, b_i) = 0, \quad i = 0, \dots, n$$
 (7)

Amazingly, all the steps to here are the same!

But now we've hit a road block, because we don't know *u*

Before, we knew f so this wasn't an issue

We will get around this with a specially chosen inner product

Global spectral methods: using the energy inner product

We will make progress by using the *energy inner product* for (7). For the 1D Poisson problem we are considering, this energy IP is defined as

$$(f,g)_E = \int_a^b f'(x)g'(x)dx, \quad \forall f,g \in \mathcal{V}$$
 $\frac{d^2u}{dx^2} = f, x \in [a,b]$

Looking at the induced norm tells us why we call this the energy IP

$$||g||_{E} = \sqrt{(g,g)_{E}} = \sqrt{\int_{a}^{b} (g'(x))^{2} dx}$$
Remember: the 1D Poisson problem is a steady state heat equation. This is a measure of the heat flux density, $-k \frac{du}{dx}$, integrated across the domain.

Note. This energy IP is specific to the 1D Poisson equation, and has to be changed for different BVPs!

Global spectral methods: Using the energy inner product to solve for the c_i

Let's use our *energy inner product* for (7):

(u,

$$(u - u_a, b_i)_E = 0, \quad i = 0, \dots, n \tag{7}$$

$$\sum_{j=0}^n c_j \left(b_j, b_i \right)_E = (u, b_i)_E, \quad i = 0, \dots, n \tag{8}$$

$$b_i)_E = \int_a^b u'(x)b_i'(x)dx$$

$$= [u'(x)b_i(x)]_a^b - \int_a^b u''(x)b_i(x)dx$$
Integration by parts, then assume the BVP has zero Dirichlet BCs and that the basis functions $b_i(x)$ preserve these BCs. Can handle the more general case with some tedium...
$$= -\int_a^b u''(x)b_i(x)dx$$

$$= -\int_a^b f(x)b_i(x)dx$$
(9)
Note that this is also an IP. Let's call it (f, b_i) ,

We can use (9) in (8) to write out a linear system for the coefficients!

$$\sum_{j=0}^{n} c_j \left(b_j, b_i \right)_E = -\left(f, b_i \right)_s, \quad i = 0, \dots, n$$
Does not include u!

Global spectral methods: Get the $c_j \implies$ approximate u

$$\implies \begin{bmatrix} (b_0, b_0)_E & (b_1, b_0)_E & \cdots & (b_{n-1}, b_0)_E & (b_n, b_0)_E \\ (b_0, b_1)_E & (b_1, b_1)_E & \cdots & (b_{n-1}, b_1)_E & (b_n, b_1)_E \\ \vdots & \vdots & \cdots & \vdots & \vdots \\ (b_0, b_{n-1})_E & (b_1, b_{n-1})_E & \cdots & (b_{n-1}, b_{n-1})_E & (b_n, b_{n-1})_E \\ (b_0, b_n)_E & (b_1, b_n)_E & \cdots & (b_{n-1}, b_n)_E & (b_n, b_n)_E \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \\ c_n \end{bmatrix} = - \begin{bmatrix} (f, b_0)_s \\ (f, b_1)_s \\ \vdots \\ (f, b_{n-1})_s \\ (f, b_n)_s \end{bmatrix}$$